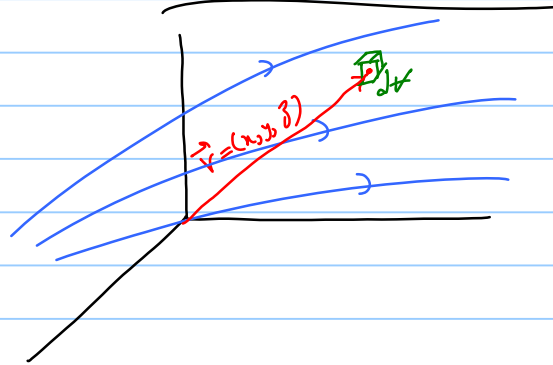


مسائل ۱ - کینماتیک ۷، ۶، ۹۹

مزم دریا نیکی مانه منشا هفتی :

$$d\vec{F} = dm \frac{d\vec{V}}{dt}$$

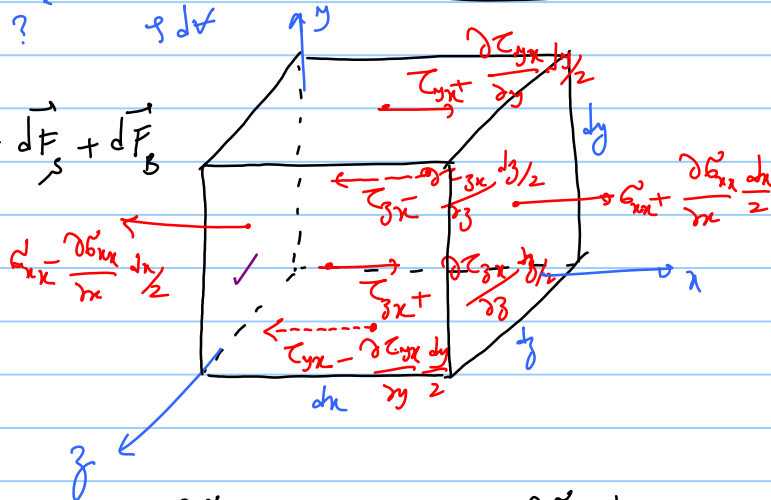
$$\vec{V} = \vec{V}(x, y, z, t)$$



$$\frac{d\vec{V}}{dt} = \vec{a} = u \frac{\partial \vec{V}}{\partial x} + v \frac{\partial \vec{V}}{\partial y} + w \frac{\partial \vec{V}}{\partial z} + \frac{\partial \vec{V}}{\partial t}$$

$$\Rightarrow d\vec{F} = dm \left(u \frac{\partial \vec{V}}{\partial x} + v \frac{\partial \vec{V}}{\partial y} + w \frac{\partial \vec{V}}{\partial z} + \frac{\partial \vec{V}}{\partial t} \right)$$

$$d\vec{F} = dF_s + dF_b$$



$$\Rightarrow dF_{s_x} = \left(\sigma_{xx} + \frac{\partial \sigma_{xx}}{\partial x} \frac{dx}{2} \right) dy dz - \left(\sigma_{xx} - \frac{\partial \sigma_{xx}}{\partial x} \frac{dx}{2} \right) dy dz$$

$$+ \left(\tau_{yx} + \frac{\partial \tau_{yx}}{\partial y} \frac{dy}{2} \right) dx dz - \left(\tau_{yx} - \frac{\partial \tau_{yx}}{\partial y} \frac{dy}{2} \right) dx dz$$

$$+ \left(\tau_{zx} + \frac{\partial \tau_{zx}}{\partial z} \frac{dz}{2} \right) dx dy - \left(\tau_{zx} - \frac{\partial \tau_{zx}}{\partial z} \frac{dz}{2} \right) dx dy$$

$$\Rightarrow dF_{s_x} = \left(\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \right) dx dy dz$$

$$dF_{b_x} = dm g_x = (\rho dV) g_x = \rho g_x dx dy dz$$

$$\Rightarrow dF_x = F_{sx} + F_{bx} = \left(\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho g_x \right) dx dy dz$$

به صورتی که بر مؤلفه یاز در راستای x در هر یک از اجزا:

$$\Rightarrow dF_y = \left(\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho g_y \right) dx dy dz$$

$$dF_z = \left(\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} + \rho g_z \right) dx dy dz$$

با استفاده از معادله حرکت:

$$x\text{-mom: } \rho g_x + \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right)$$

$$y\text{-mom: } \rho g_y + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} = \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right)$$

$$z\text{-mom: } \rho g_z + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} = \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right)$$

فرا برداریم معادله حرکت:

با فرض سیال نیرتزن میزنده حرکت: $\tau_{xy} = \tau_{yx} = \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$

$$\tau_{xy} = \tau_{yx} = \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$

$$\tau_{yz} = \tau_{zy} = \mu \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)$$

$$\tau_{zx} = \tau_{xz} = \mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)$$

همچنین اشیاء کشنده بر سیال نیرتزن:

$$\sigma_{xx} = -p - \frac{2}{3} \mu \nabla \cdot \vec{v} + 2\mu \frac{\partial u}{\partial x}$$

$$\sigma_{yy} = -p - \frac{2}{3} \mu \nabla \cdot \vec{v} + 2\mu \frac{\partial v}{\partial y}$$

$$\sigma_{zz} = -p - \frac{2}{3} \mu \nabla \cdot \vec{v} + 2\mu \frac{\partial w}{\partial z}$$

با استفاده از معادله حرکت نیرتزن در فرا برداریم معادله حرکت:

نادره است که نتایج فزاینده:

معادلات ناور-استوکس :

$$\rho \frac{Du}{Dt} = \rho g_x - \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left[\mu \left(2 \frac{\partial u}{\partial x} - \frac{2}{3} \vec{v} \cdot \vec{v} \right) + \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + \frac{\partial}{\partial z} \left[\mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right] \right]$$

$$\rho \frac{Dv}{Dt} = \rho g_y - \frac{\partial p}{\partial y} + \frac{\partial}{\partial x} \left[\mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + \frac{\partial}{\partial y} \left[\mu \left(2 \frac{\partial v}{\partial y} - \frac{2}{3} \vec{v} \cdot \vec{v} \right) + \frac{\partial}{\partial z} \left[\mu \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \right] \right]$$

$$\rho \frac{Dw}{Dt} = \rho g_z - \frac{\partial p}{\partial z} + \frac{\partial}{\partial x} \left[\mu \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) \right] + \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) \right] + \frac{\partial}{\partial z} \left[\mu \left(2 \frac{\partial w}{\partial z} - \frac{2}{3} \vec{v} \cdot \vec{v} \right) \right]$$

معادلات ناور-استوکس بصورت ماتریکس:

$$\rho \frac{D\vec{v}}{Dt} = -\vec{\nabla} p + \mu \nabla^2 \vec{v} + \rho \vec{g}$$

$$\rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \rho g_x$$

$$\rho \frac{Dv}{Dt} = -\frac{\partial p}{\partial y} + \mu \nabla^2 v + \rho g_y$$

$$\rho \frac{Dw}{Dt} = -\frac{\partial p}{\partial z} + \mu \nabla^2 w + \rho g_z$$

$$\rho \frac{D\vec{v}}{Dt} = -\vec{\nabla} p + \mu \nabla^2 \vec{v} + \rho \vec{g}$$

P, u, v, w متغیرهای اسکالر ←

\vec{v} متغیر ناور-استوکس بصورت ماتریکس:

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial p}{\partial r} + \rho g_r$$

$$+ \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_r}{\partial r} \right) - \frac{v_r}{r^2} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \rho g_\theta$$

$$+ \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_\theta}{\partial r} \right) - \frac{v_\theta}{r^2} + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \rho g_z$$

$$+ \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right]$$

$w, v, u \neq P$

